## FROM TC10 TO SYSTEM WAKE-UP SAFETY SYSTEM SOLUTIONS

ETHERNET & IP @ AUTOMOTIVE TECHNOLOGY DAY

Steffen Lorenz NOVEMBER 2022



PUBLIC

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#### AGENDA

- Motivation/Introduction
- Sleep & Wakeup concepts
- Functional Safety
- Zonal system aspects
- Summary and conclusion

#### ARCHITECTURE IS SHIFTING TOWARDS ETHERNET-BASED ZONAL MODEL



#### ARCHITECTURE IS SHIFTING TOWARDS ETHERNET-BASED ZONAL MODEL



- · Availability of nodes handled by domain controller
- Nodes of a function mostly in same network
- X-domain wakeup handled by central gateway



- Service oriented availability requests
- Nodes are spread over whole network
- wakeup to be handled by zonal gateways

#### ZONAL GATEWAY / ZONAL AGGREGATOR



- Aggregation of data & gateway function
- Connects diverse technologies
  - (Switched) Point-to-Point Ethernet
  - 10BASE-T1S
  - CAN
- ...
- Connects to high-speed backbone
- Connections belong to several functional domains
- And it consumes power!
- $\rightarrow$  Switch off parts, which are not needed

# Sleep and Wakeup Concepts



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#### **TC10 WAKEUP 100/1000BASE-T1**

- Sleep/Wake on PHY level
  - defined by TC10 of OPEN Alliance
  - 100BASE-T1 & 1000BASE-T1
- Partial sleep
  - Negotiation on NM level
  - sleep handshake on PHY level
- Fast forwarding on PHY level
  - Linkup parallel to ECU startup
  - Wakeup over an active link (WUR)



#### **TC10 WAKEUP 100/1000BASE-T1**

- PHY centric concept, but can control whole ECU
- Unused ports can be switched off to safe power
- Ports can be woken up remotely
- Wakeup forwarding to wake remote PHYs
- If all ports are off, switch can be switched off
- The MCU may be off as well,
  - with or without communication running
  - with local or remote wakeup (via TC10)
- Whole ECU may be in Sleep, wakeable via remote wakeup



# **Functional Safety**



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## ISO 26262 – The Science of Quantifying Risk



## FUNCTIONAL SAFETY SAFETY GOALS Severity Hazard Analysis & Risk Assessment Exposure $\rightarrow$ Performed on item level $\rightarrow$ requirements assigned in Safety concept to ensure safety goals $\rightarrow$ inherited to lower-level sub-system/components Controllability $\rightarrow$ Typically relevant on Ethernet Unintended frame/data insertion Unintended frame corruption Undetected frame loss Unintended frame delay, repetition or sequencing



### HOW THE NETWORKING IC BRINGS SAFETY TO THE ZONE

Vehicle service availability can be improved by ensuring the availability of communication services in the vehicle. Networking chips can:

- Prevent Failure
  - Very high reliability
  - Freedom from interference
- Predict Failure
  - (Self-)Diagnostic features
- React to Failure
  - Quickest response time to increase FTTI margin
  - Even correct some failures



#### HOW THE NETWORKING IC BRINGS SAFETY TO THE ZONE

### Prevent Failure

- Manufacturing quality makes the difference
- Policing / access control
- Configuration monitoring

#### Predict Failure

- Build-in self-test
- Temperature/Voltage monitoring
- Counter/diagnosis monitoring
- Latent fault tests

### React to Failure

- Memory failure correction (ECC)
- IEEE 802.1CB (stream replication/elimination)
- Even correct some failures
- Entering safe state (for sub-system)

Example Reference FIT calculation		For T pleas	For Tjv / CL parameter details, please contact NXP	
TJA1043U	Siemens Norm SN29500	HTOL Qual CAN Family	Production & Field Return Data CAN Family	
Reference FIT calculation	42 FIT	3.0 FIT	0.04 FIT	



## System view Functional Safety & Sleep



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- Example for a zonal controller
  - Several communication interfaces
  - Switch for high-speed data links
  - MCU for local pre-processing and data aggregation of local networks
  - Power controller (PMIC) for supply
- Safety requirements on the communication and processing



xBASE-T1 10BASE-T1S CAN/LIN/other

- Standalone communication
  - In case no local processing needed, e.g. charging, ADAS functions off,...
  - MCU and related peripheral is off
  - Communication is active
    - Functional Safety of communication subsystem must be independent from MCU
    - Requires safety compute in the switch
    - PMIC is supervising the switch



xBASE-T1 10BASE-T1S CAN/LIN/other

- Standalone processing / data aggregation
  - In case no high-speed communication needed, e.g. local ...
  - MCU and related peripheral is active
  - Communication is off
    - Functional Safety runs in the active subsystem
    - Independent from back-bone communication
    - PMIC is supervising the MCU



xBASE-T1 10BASE-T1S CAN/LIN/other

- Wakeup from diverse sources
  - System wakeup may be requested from local network, central brain or another zonal controller.
  - Required action differs between wakeup sources

- Wakeup reaction must allow for flexible wakeup reaction
- Allow for independent operation
- Further wakeup may be situation dependent



xBASE-T1 10BASE-T1S CAN/LIN/other

- Example
  - Wakeup from 10BASE-T1S
  - Communication with "central brain" is required
  - Later the "brain" requests full operation

- 1. Wakeup from 10BASE-T1S
- 2. Forward to related PHY port and wakeup switch
- 3. Build up link and start communication
- 4. Wakeup MCU by switch on request



xBASE-T1 10BASE-T1S CAN/LIN/other



### SUMMARY AND CONCLUSIONS

- Zonal architectures bring new challenges functions are spread over the network
- Partial sleep/standby scenarios are required for power savings
- Functional safety concepts must address
  mixed safety level of communication
- Functional safety concepts must consider part of the network not always being available
- System solutions will help addressing this challenge



## SECURE CONNECTIONS FOR A SMARTER WORLD

